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I3 I 3 I. (1 + i2) i (1 + i2) = 0 Let q = 1 + i2 Now q iq = 0 has solution q (t) = Aeit this is 1 + i2 = A cos t + iA sin t and we see 1 (t) = A cos t 2 (t) = A sin t The x3 axis is the symmetry axis of the body, so the angular velocity vector precesses about the body x3 axis with a constant angular frequency = 1.

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